

# CSE 599S Proof Complexity & Applications

Lecture 11

4 Nov 2020

## Conflict-Directed Clause-Learning (CDCL) Solver

Recall:

call DPLL( $F, n, i$ )

DPLL( $F, A$ )  
 while  $F$  contains a clause  $x$  of size 1 do  
 $F \leftarrow F_{x+1}; A \leftarrow (A \setminus x)$   
 if  $F$  is empty then  
 halt and output set  $A$

If  $F$  contains the empty clause 1  
 then return add clause

else choose unsat literal  $x$

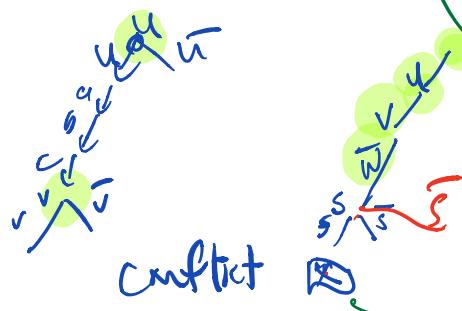
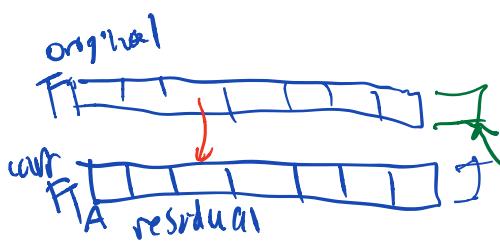
DPLL( $F_{x+1}, (A, x)$ )

DPLL( $F_{x+1}, (A, \bar{x})$ )

decide  $A = u, v, \bar{w}, \bar{s}, c$

learn

$\bar{w} \vee \bar{v} \vee w \vee \bar{s}$   
 unit prop creates  
 higher up the tree



add

Modified form : at each leaf (conflict) add  
clause with negative of all decisions  
made to get to leaf.  
 move up to 1st level above  
 this unit propagates.  
 replaces last decision with new prop.

We can learn better clauses than negation of decisions

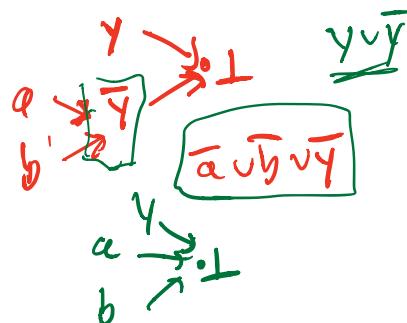
## Conflict Graph :

Balck on  
original F

## Decision (lateral) sources

Add a node at every unit prop.

$$C = (x \vee \bar{y} \vee z) \xrightarrow{\text{A}} \begin{matrix} y=1 \\ z=0 \end{matrix} \quad \text{unit } x$$

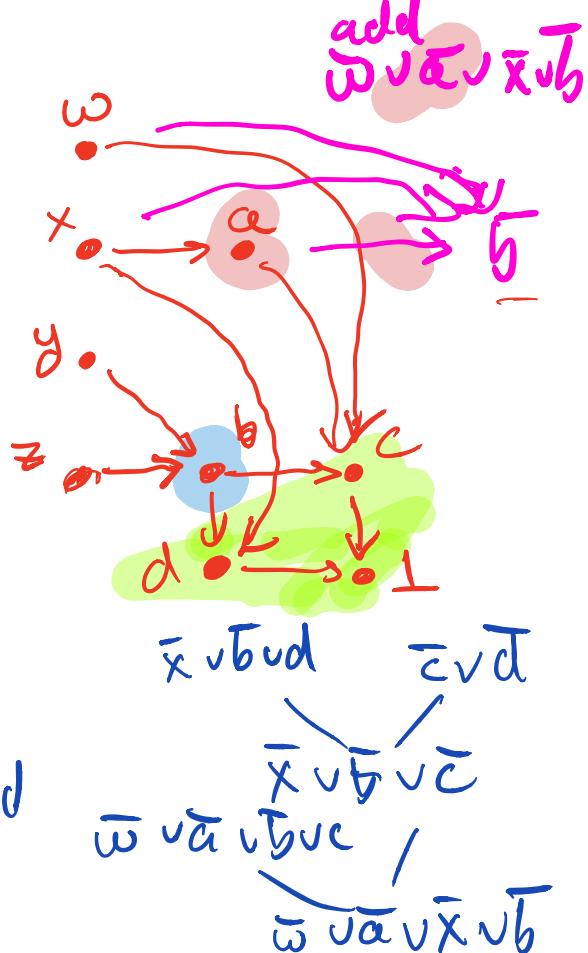


Example next page

$$F: \overline{w} \vee \overline{a} \vee \overline{b} \vee c, \overline{x} \vee a, \overline{x} \vee \overline{b} \vee d, \\ \overline{y} \vee \overline{z} \vee b, \overline{c} \vee \overline{d}, \overline{w} \vee \overline{x} \vee \overline{b}$$

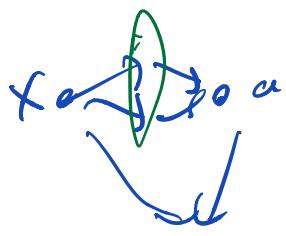
| Decision Level | Decision    | Conflict Graph | $\overline{w} \vee \overline{x} \vee \overline{b}$ |
|----------------|-------------|----------------|--|
| 0              | $\emptyset$ |                |  |
| 1              | w           |                |  |
| 2              | x           |                |  |
| 3              | y           |                |  |
| 4              | z           |                |  |

any cut in conflict graph  
with all decisions present  
on one side  
empty clause on other  
that is cleared  
corresponds to clause  
that could be added  
to F



Want to choose a clause that won't propagate  
at a higher level  
just want 1 literal at this level  
\* agivating clauses

$\overline{w} \vee \overline{a} \vee \overline{x} \vee \overline{b}$  ULP "1st unique implication point"  
GRASP working back from 1  
 Clause associated with net just after 1st  
 node separated last decision from 1



Learned Clause Minimization (MinSAT)  
allows removal of rare literals  
from the learned

$$\bar{w} \vee \bar{a} \vee \bar{x} \vee b \quad \bar{x} \vee a$$

$$\bar{w} \vee \bar{x} \vee b$$

Then Resolutor simulates CDCL

Implementation:

- learned clauses
- big. sometimes ✓
- many of them ⚡

Last evaluation: Don't keep residual formula  
Chaff 2000-2001 Only keep 2 watched literal per clause



If a watched literal is set to false  
search for another literal to watch  
If none available: unit propagated

2 literals / clause in cache.

DIMACS var uses: integers  $\pm$  sign  
 Formed -1 2 3  $\bar{x}_1 \vee x_2 \vee x_3$

Assignment A: "fresh"  
is also in cache

## Decision heuristic:

VSIDS  
variable sum decaying

priority queue

count for each

var



+ 1 every time a var appears in  
a learned clause  
periodically divide all counts by 2  
(every 256 conflicts) changed

multiplicative weight updates

choose "phase" of the variable

- phase saving
- set var to the sign it was last set

## Learned clause deletion:



If a clause hasn't been  
touched recently  
throw it away

Periodically cut set of learned  
clauses by  $\frac{1}{2}$   
cut long clauses.

Restarts      (why so many backtracks)  
 $F$  learned clauses  
 restart at level 0.  
 e.g. learned unit clause  $X$

Glucose      "literal block listans"  
 heuristic

Then CDCL + phase saving + nondet  
 branching  
 can simulate resolutions  
 $O(a^3)$  restarts per  
 resolution step

Then CDCL is not prepared under  
 restrictions

$F_\alpha$       may be harder for  
 truth assignment      CDCL  
 than  $F_\beta$   
and/or , - .

Run  $F + G$  · No restarts  
 new variables  
 $\uparrow$  CDDL  
 doesn't depend on  $F$  · simulated  
 SAT.  
 resolution  
 $O(n^2)$   
 steps  
 per resolution  
 clause

In practice CDCL still has  
 major problems on  
 Tseitin example even  
 with polysize proofs

